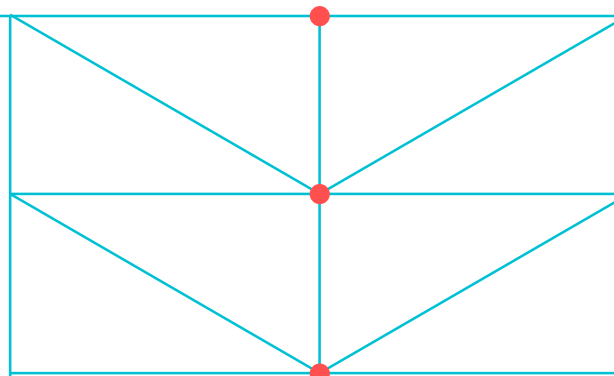


Dynamic Resource Allocation for 5G Device-to-Device Communication Based on Expected SARSA



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Technische
Universität
Hamburg



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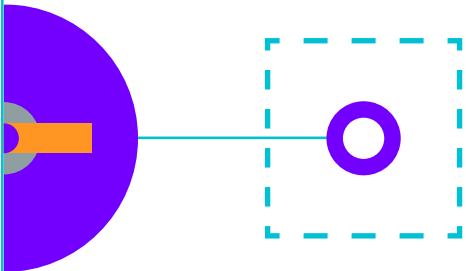
Presented by: Shashini Thamarasie Wanniarachchi



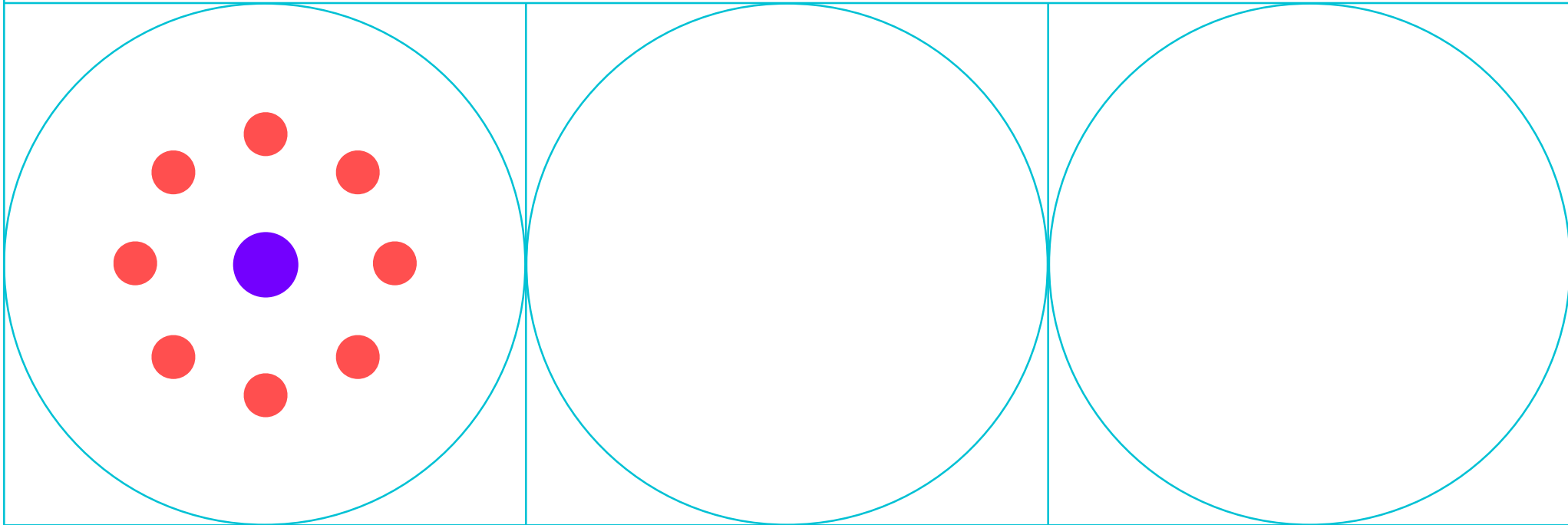
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2. Objectives
3. Methodology
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5. Conclusion & Outlook



1. Background



Background

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- Problem: Increasing demand on communication and mobile device usage overwhelm the base station
- Solution: Usage of Device-to-Device (D2D) communication
- Issues with D2D communication that hinder user experience
 - ◊ Peer Discovery
 - ◊ Interference Management
- Components contributing to interference management
 - ◊ Resource Allocation
 - ◊ Resource Management
 - ◊ Power Control

Background

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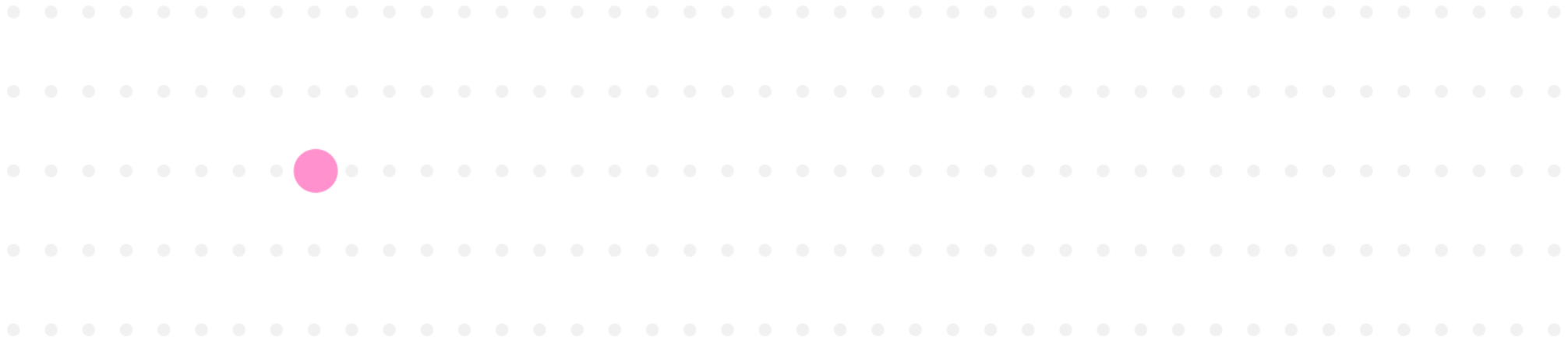
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2. Objectives

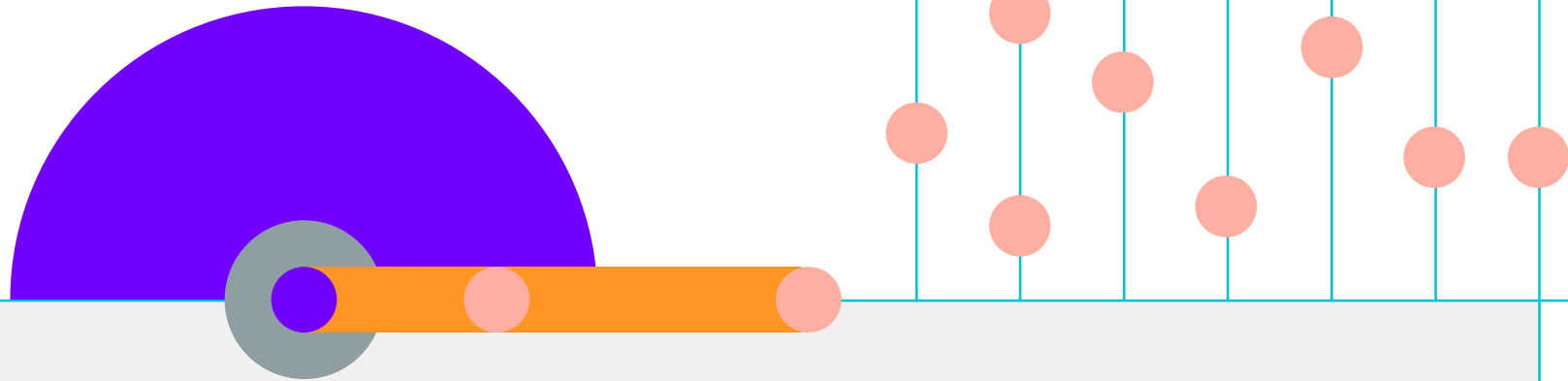


Objectives

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- Analyzing the available strategies of resource allocation for D2D communication
- Developing a mechanism for dynamic resource allocation for network authorized underlay D2D communication to realize a high system performance in terms of
 - ◊ Achieved throughput
 - ◊ Signal-to-noise ratio
 - ◊ Delivery delay
 - ◊ Delivery ratio

3. Methodology

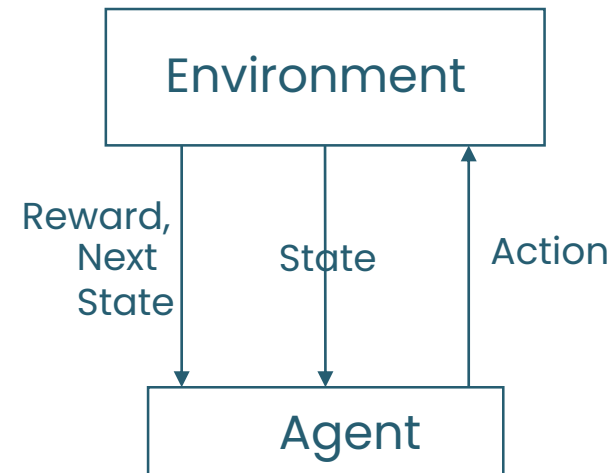


Methodology

- Proposed method: Applying **Expected SARSA** reinforcement learning algorithm for dynamic resource allocation in 5G D2D communication

Reinforcement Learning

- Consists of 5 elements : state, action, reward, agent and environment
- Concept: Searching for the optimal policy depending on the rewards gained by performing actions in a certain state



Methodology

SARSA

- Stands for:
State–Action–Reward–Next State–Next Action
- On-policy exploration method
- Q value: Return expected for taking a certain action in a certain state following the policy

Expected SARSA

- Extension of SARSA
- Consider the weighted average of Q-values of all possible actions in the next state for Q-value estimation
- Reduced variance
- Converges faster
- Requires less training

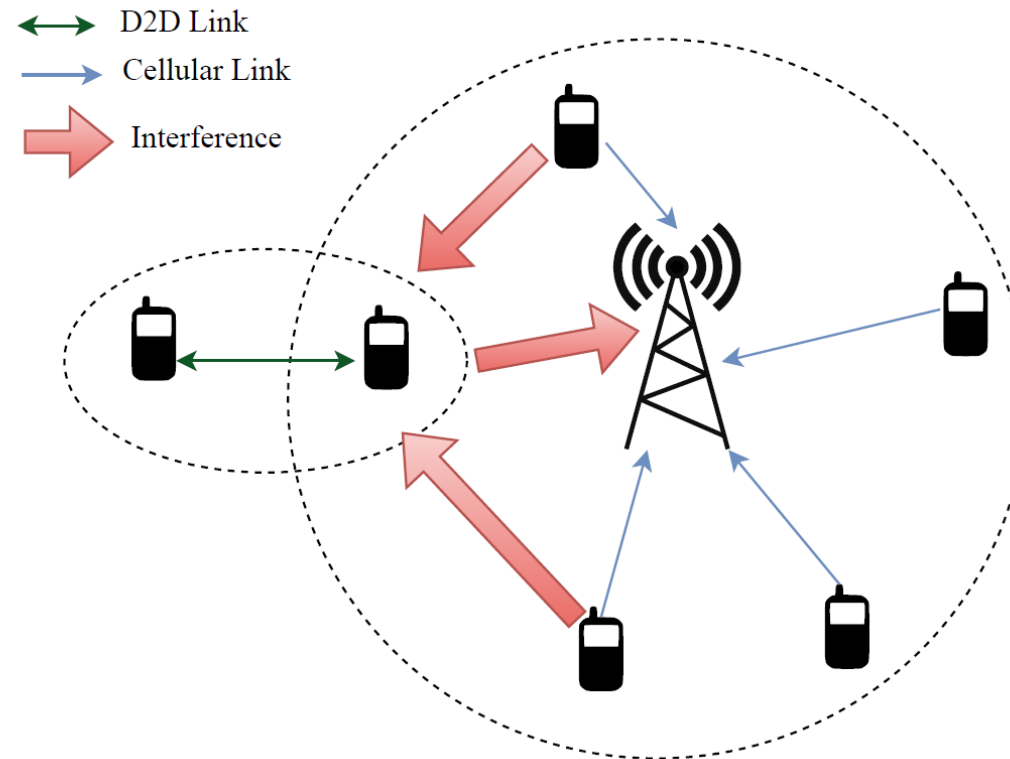
Methodology | Expected SARSA

- Agent observes the current state
- Agent selects an action according to the policy : ϵ – Greedy policy
- ϵ – Greedy policy :
 - ◊ $0 \leq \epsilon \leq 1$
 - ◊ With probability $1-\epsilon$: Action with the highest estimated Q-value (Exploitation)
 - ◊ Else : Random action selection (Exploration)
- Agent observes the obtained reward for the action taken and the next state
- Agent estimates the Q-values
- Agent update the policy for the current state based on estimated Q-values

Methodology | Implementation

Scenario Definition

- One D2D pair and number of interfering devices
- Simulation duration : 30 s
- Packet size : 1000 bytes
- Transmission protocol : UDP
- Base station transmission power: 46dBm
- Simulation framework :
 - ◇ OMNeT ++ (version 6.0) [\[1\]](#)
 - ◇ Simu5g (version 1.2.1) [\[2\]](#)



Methodology | Implementation

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Other Parameters

- Distance between base station and D2D user pair: 50m
- Mobility model: Mass Mobility
- Two methods in comparison :

Default Case

- Default setup in simu5G
- Carrier frequency: 2GHz
- Number of resource blocks: 50
- Numerology index: 0
- Bandwidth: 5 MHz
- D2D transmission power: 26 dBm

Our Work

- Carrier frequency: 2GHz
- The following parameters are changed according the [table](#)
 - Number of resource blocks
 - Numerology index
 - Bandwidth
 - D2D transmission power

Methodology | Implementation

Considered Parameters for Expected SARSA

- Number of states = 3
- In our work: State and reward functions are based on [system throughput](#)
- Number of actions = 5
- Action consists of Number of resource blocks, Numerology index and Transmission power
- Action space:

Action	Bandwidth (MHz)	Number of Resource Blocks	Numerology Index	Transmission Power (dBm)
1	25	125	0	23
2	20	100	0	23
3	20	50	1	26
4	5	25	0	26
5	30	75	1	26

Methodology | Implementation

Experiment	Parameter	Considered values
Average throughput comparison of our work and default case	D2D pair distance(dD2D)	20m , 40m, 60m
	Number of Interfering Devices (NI)	None, 10, 25
SNR result comparison of our work and default case	dD2D	20 m
	NI	25
Reliability and delay assessment	dD2D	60 m
	NI	25
Investigating the impact of mobility	3 cases	Mobile D2D, No NI
		Mobile D2D NI: 25 & stationary
		Mobile D2D NI: 25 & mobile

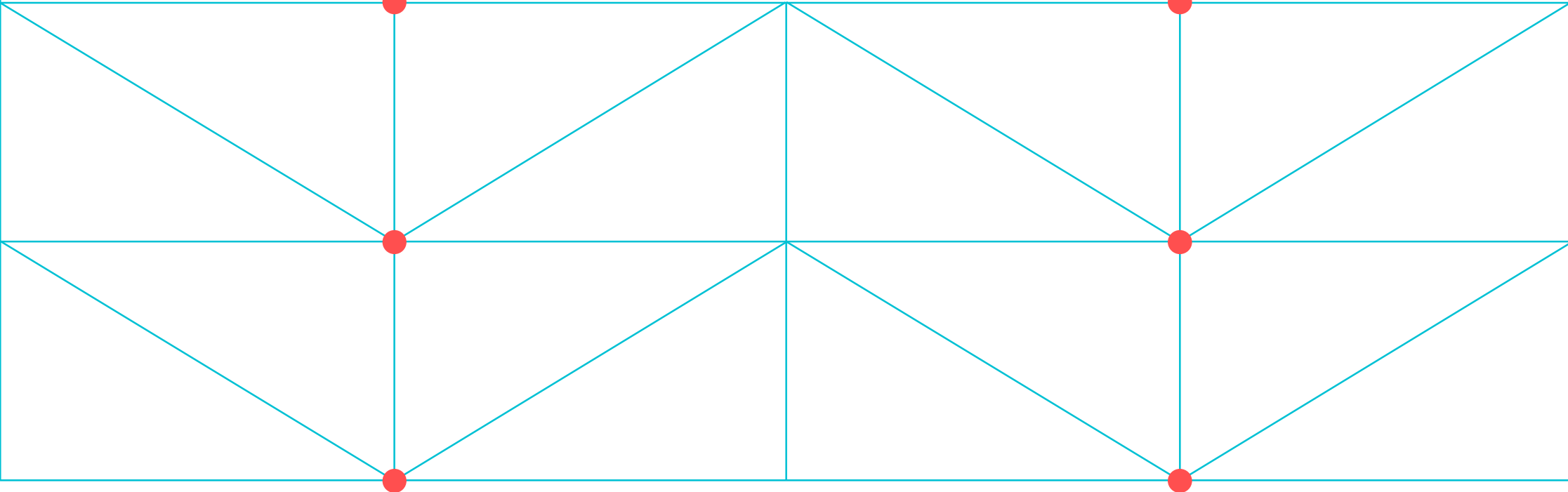
Methodology | Implementation

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Performance Evaluation Criteria

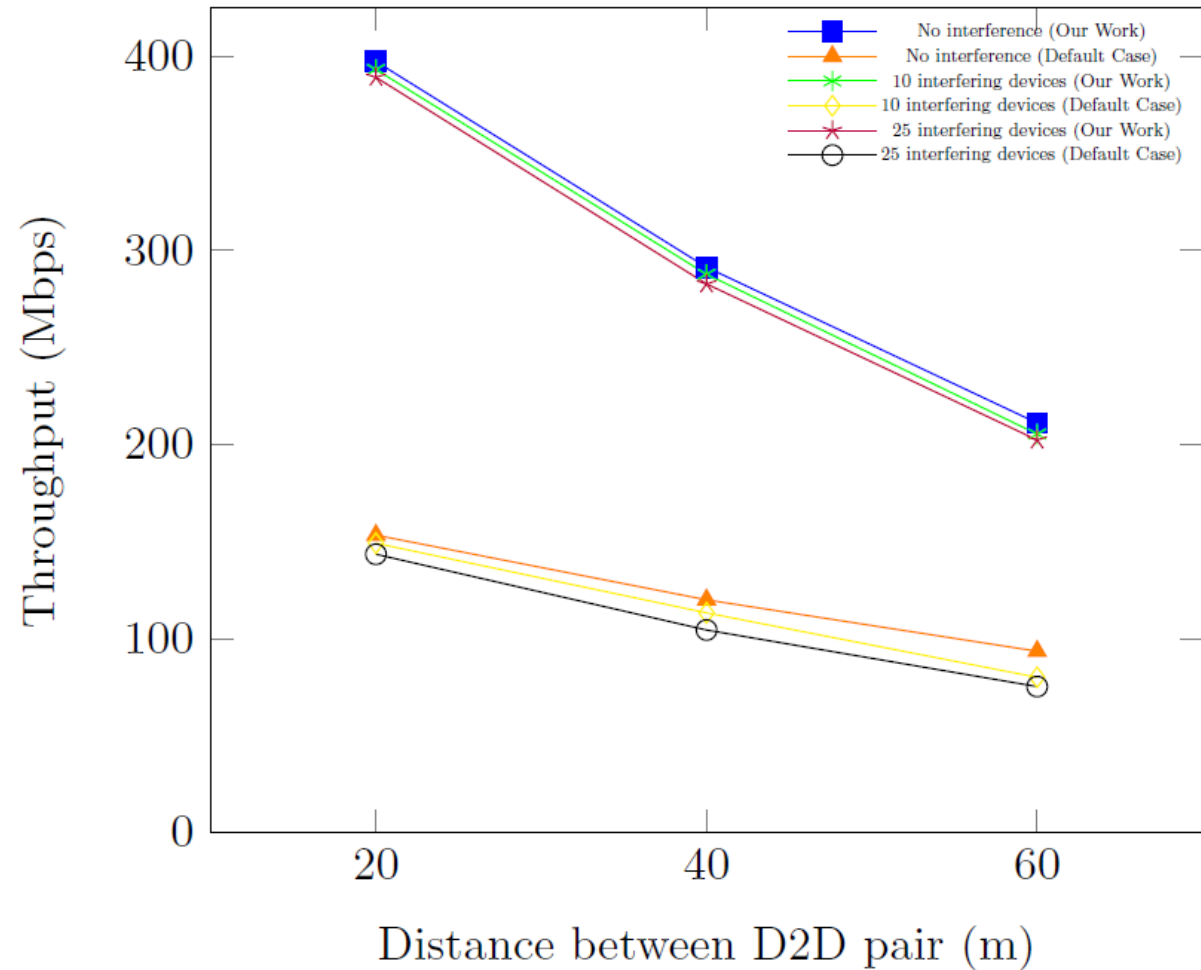
- System throughput (Mbps)
- Signal to noise ratio
- Delivery delay (ms)
- Delivery ratio

4. Results



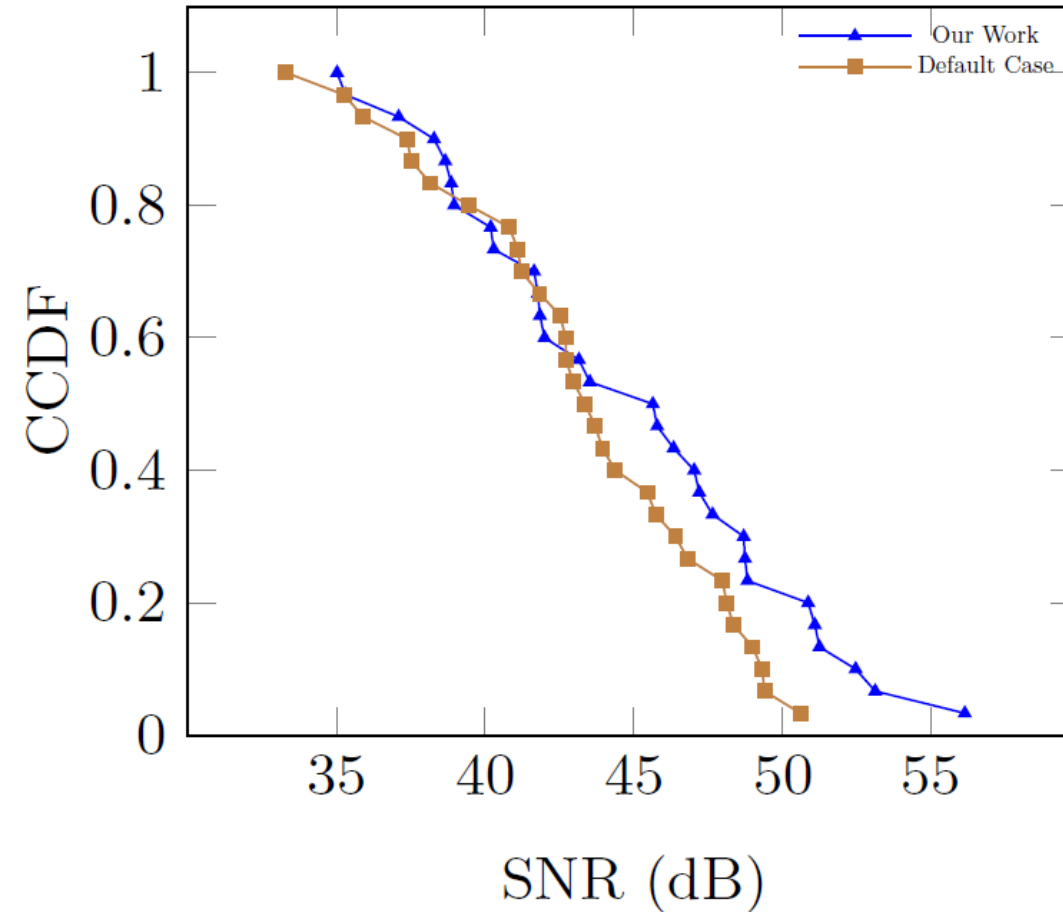
Results

Average D2D throughput comparison for various distances between the D2D pair with different interference scenarios



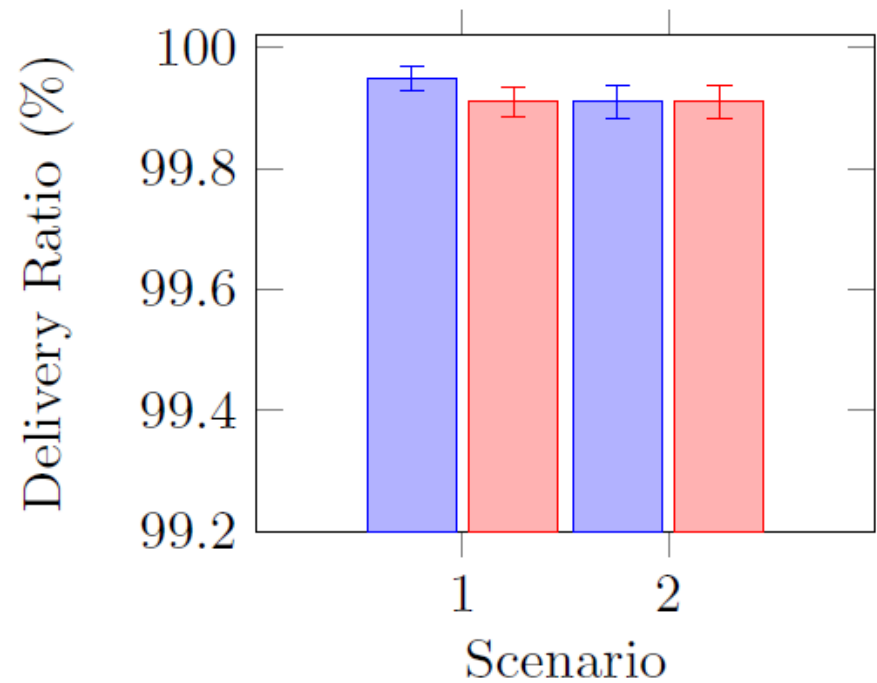
Results

CCDF plot of measured SNR with 25 interfering devices for a 20 m D2D pair distance

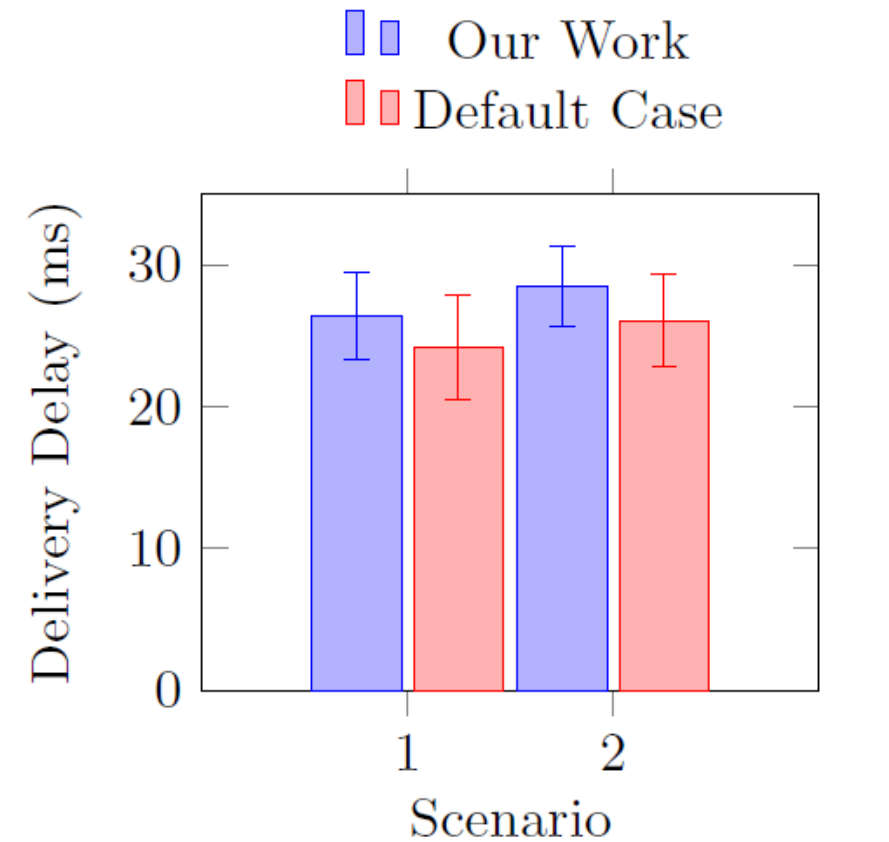


Results

Reliability and delay assessment



Average Delivery Ratio (%)



Average Delivery Delay (ms)

Investigating the impact of mobility

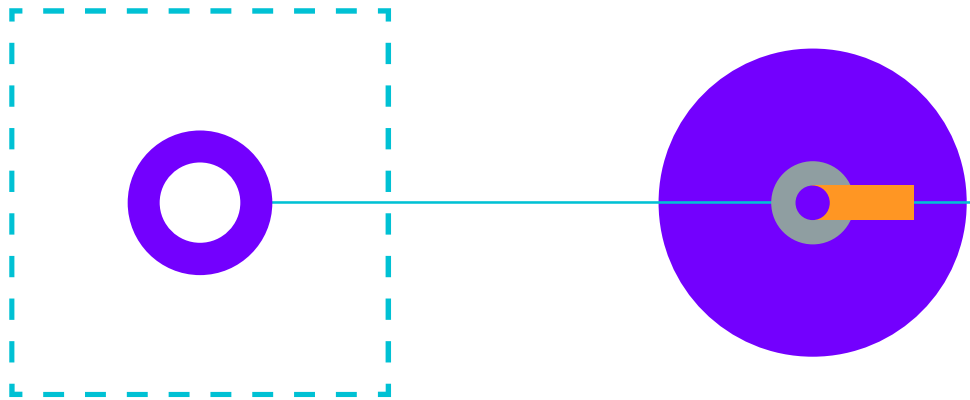
Scenario	No Interference	25 Stationary Interfering Devices	25 Mobile Interfering Devices
Our Work	294.25 Mbps	292.78 Mbps	293.78 Mbps
Default Case	113.60 Mbps	114.23 Mbps	115.33 Mbps

Results – Remarks on the Simulation

Computational Complexity

- **Compared to default case:**
 - **Time required for simulation:** 3 times higher
 - **Additional memory consumption:** 15 %
- **Time required to simulate 30 s:** 1 min in real time
- **Memory consumption:** 38%

5. Conclusion & Outlook



Conclusion & Outlook

Conclusion

- Proposed algorithm delivers improved system throughput with high reliability
- Slight degradation of delivery delay values
- Computational complexity of the algorithm stands within a tolerable range
- Expected SARSA based resource allocation enhance performance with reduced interference in 5G D2D

Outlook

- Extend the concept with multiple D2D user pairs
- Analysis with real mobility scenarios
- Implement and evaluate the case of switching carrier frequency and other parameters
- Study the means of degrading delivery delay alongside applying our algorithm

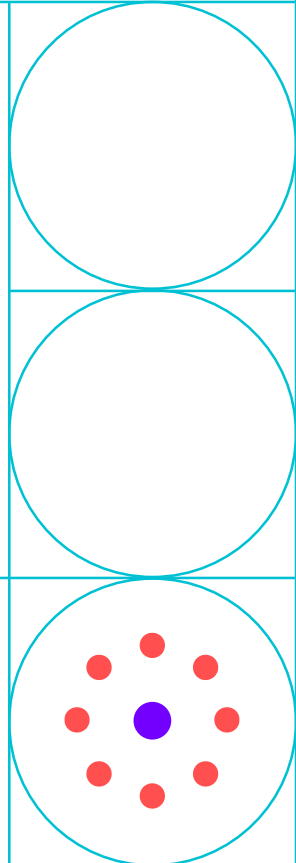
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Thank you for
your attention

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Methodology | Expected SARSA

$$Q(S_t, A_t) \leftarrow Q(S_t, A_t) + \alpha[R + \gamma(\sum_{A_t \in \delta_t} \Pi(A_t|S_{t+1})Q(S_{t+1}, A_t) - Q(S_t, A_t))]$$

S_t = Current state

A_t = Current action

R = Reward

S_{t+1} = Next state

A_{t+1} = Next action

Π = ϵ - Greedy policy, where $0 \leq \epsilon \leq 1$

α = Learning rate (0.5)

δ_t = Set of all actions applicable in state S_t

γ = Discount factor (0.99)

- State and reward functions depend upon throughput

$$\text{Throughput} = B \log_2(1 + \text{SNR})$$

$$\text{SNR} = \frac{\text{Transmitted Power}}{N_0 + \Sigma I}$$

ΣI = summation of total interference at the receiving end

$$B = 2^\mu \frac{\text{Number of Resource Blocks}}{5}$$

μ = Numerology index

Performance Metrics

- System Throughput: The amount the data transmitted over a communication link within a certain time period
- Signal-to-noise ratio: Ratio of signal power to noise power
- Delivery ratio: The ratio of delivered packets to the number of generated packets
- Delivery delay: The time difference between actual packet generation and reception