Using RTAI/LXRT for Partitioning in a Prototype Implementation of the DECOS Architecture

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Overview

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- DECOS Integrated Architecture
- DECOS Component Model
- Two Dimensions of Partitioning
- Prototype Implementation
- RTAI/LXRT Execution Environment
- Results

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The DECOS Integrated Architecture

- Dependable Embedded COmponents and Systems
- Research project founded by the European Commission under FP6
- Architecture for distributed embedded real-time systems mainly aimed at automotive and avionics domain
- An integrated architecture that combines the benefits of integrated and federated architectures

Job Job Job Job Job Job Job Job **High-Level Services** Encapsulation, Virtual Networks, Diagnosis, Core Services C1 Predictable Message Transport C2 Fault-Tolerant Clock Synchronization C3 Strong Fault Isolation Consistent Diagnosis of Failing Nodes Time-Triggered Core Architecture Hiding of implementation details from the application, thereby extending the range of implementation choices (e.g. TTP/C, Time-Triggered Ethernet)

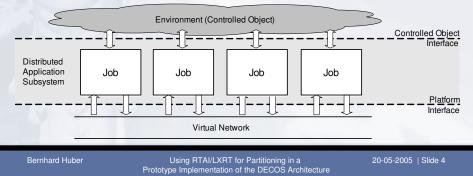
Application

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Distributed Application Subsystem

- Nearly independent distributed subsystem
- Exploit specific platform services
- Infrastructure tailored to the needs of the DAS (e.g., TT or CAN communication)



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Federated System vs. Integrated System

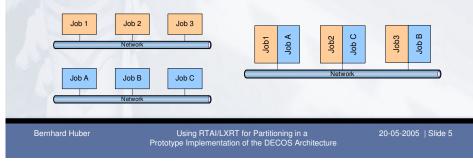
• Federated Architecture: Each DAS has its own distributed computer system, i.e. a dedicated communication infrastructure, dedicated hardware elements etc.

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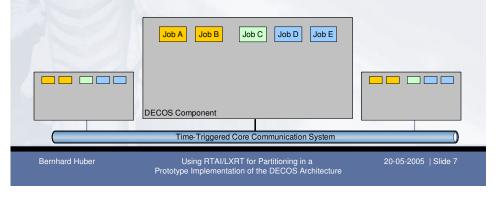
• Integrated Architecture: Multiple DASs (possibly with different criticality levels) are integrated within a single distributed computer system.



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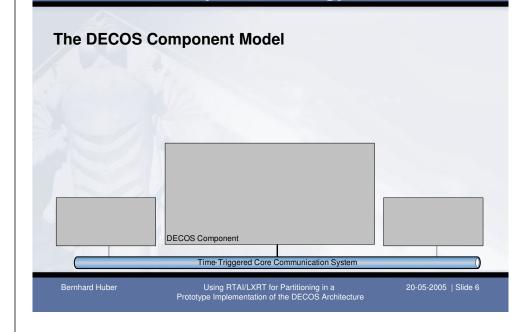
The DECOS Component Model

Jobs of different DASs hosted on the same component



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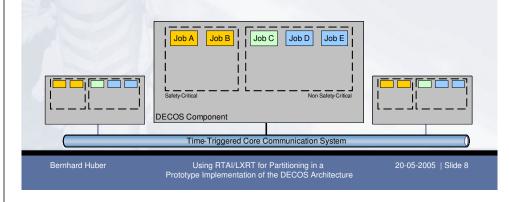
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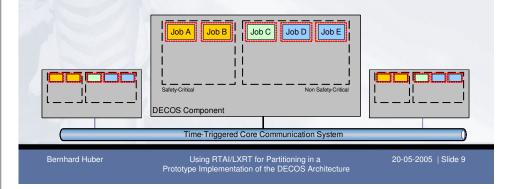
The DECOS Component Model

- · Jobs of different DASs hosted on the same component
- Support for mixed criticality



The DECOS Component Model

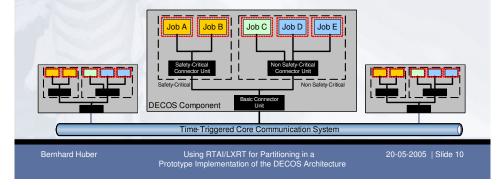
- Jobs of different DASs hosted on the same component
- Support for mixed criticality
- Encapsulated Execution Environment for each Job



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The DECOS Component Model

- Jobs of different DASs hosted on the same component
- Support for mixed criticality .
- Encapsulated Execution Environment for each Job
- Encapsulated Virtual Communication Service for each DAS



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Two Dimensions of Partitioning

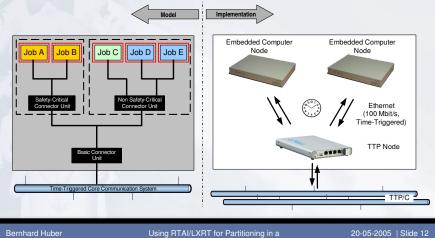
- **Spatial Partitioning**
 - Preventing jobs from overwriting memory elements of other jobs (data and code) ٠
 - Preventing jobs from interfering with other jobs in the access of devices

Temporal Partitioning

Preventing jobs from disturbing the timing of other jobs (e.g. by holding a shared • resource like the CPU)

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Prototype Implementation



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Prototype Implementation of the DECOS Architecture

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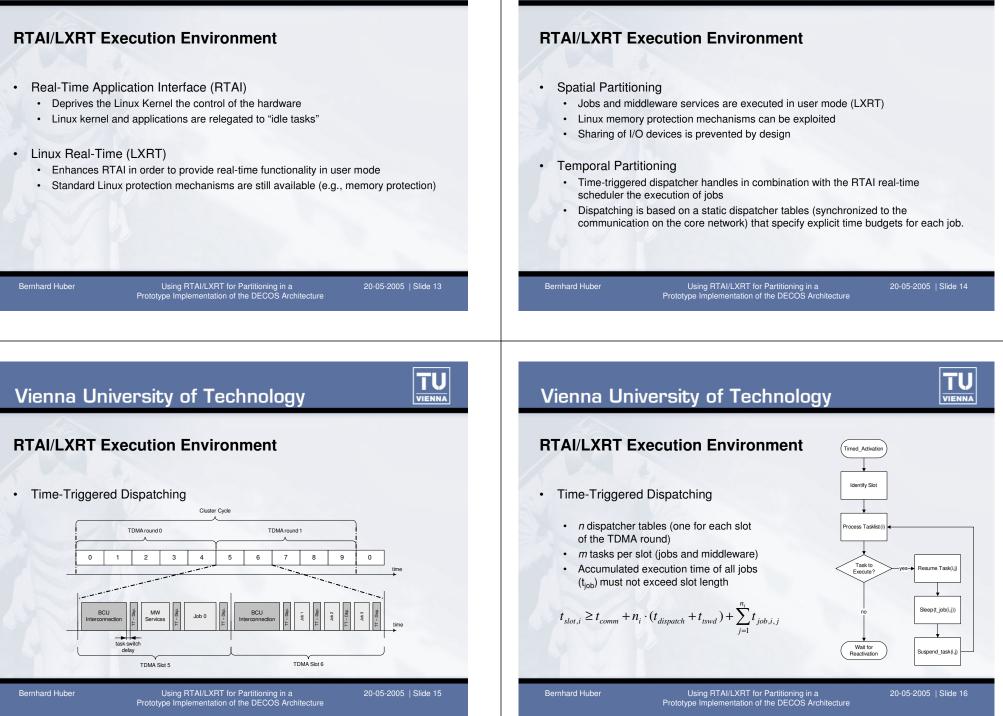
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Results

- Independence between Partitions
 - No constraints on execution time of jobs they cannot exceed their assigned time budget
 - Memory Protection is ensured by operating system mechanisms
 - Unexpected termination of any job has no influence on other jobs or middleware
- Overhead
 - Minimal and constant overhead introduced by the time-triggered dispatcher (18µs)
 - Low overhead introduced by RTAI task switch (40µs to 65µs)
- Transparency to Jobs and Middleware
 - Jobs and middleware are developed as "usual" Linux applications
 - Intellectual property (IP) protection is supported
 - RTAI/LXRT specific functionality is linked at system integration

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Thank you for your attention!

Any Questions?